



## Absolute Maximum Ratings

over operating free-air temperature range

		MIN	MAX	UNIT
Power supply voltage	VDD	-0.5	30	V
Output terminal voltage	OUT	-0.5	40	V
Output terminal current sink	I <sub>SINK</sub>	0	30	mA
Operating junction temperature, T <sub>J</sub>		-40	175	°C
Tstg		-65	150	°C
V <sub>ESD</sub>	HBM ESD stress voltage	-4.0	4.0	kV
	MM ESD stress voltage	-400	400	V

## Electrical Characteristics

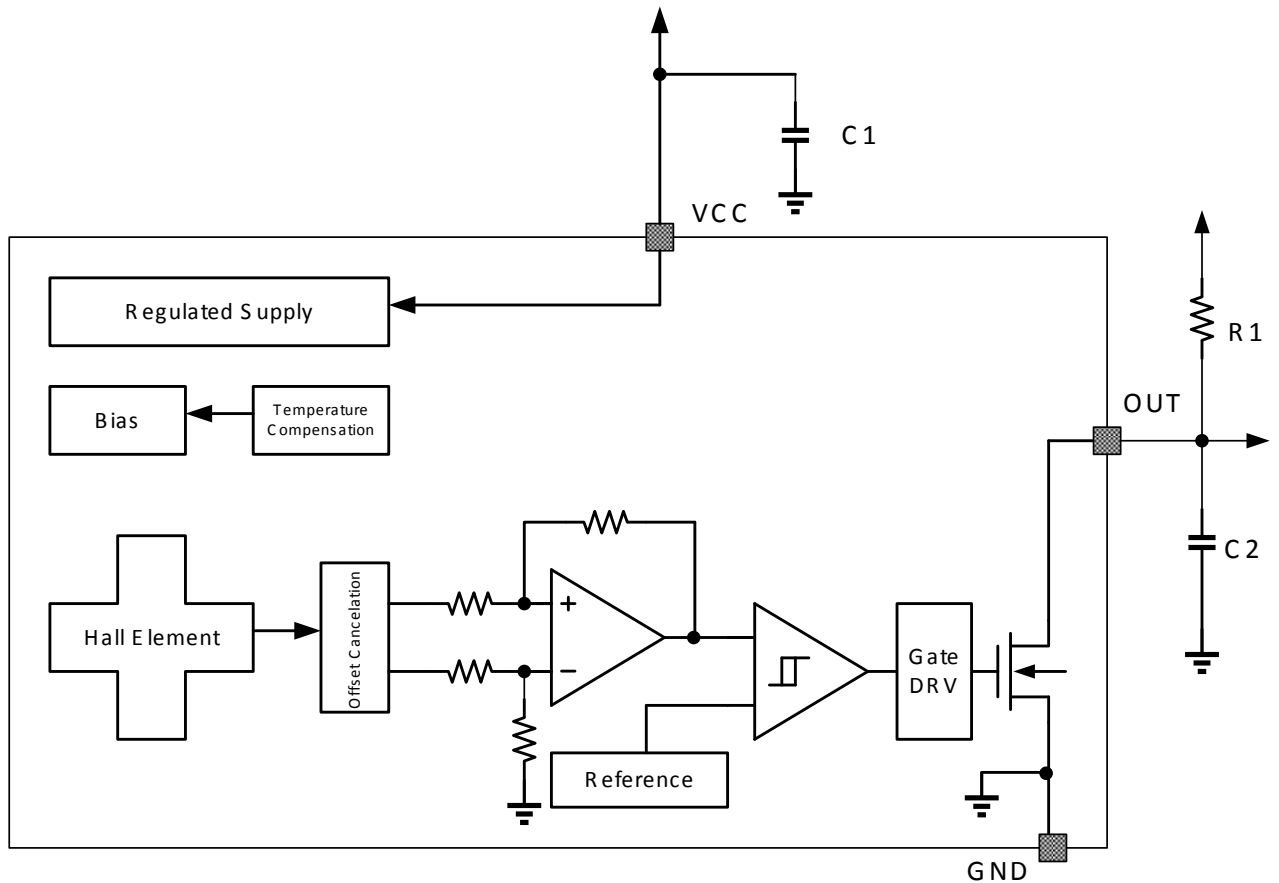
over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>DD</sub>	Operating voltage		2.5	--	24	V
I <sub>DD</sub>	Operating supply current	V <sub>DD</sub> =2.5V to 24 V	1	1.5	3.5	mA
t <sub>on</sub>	Power-on time		--	35	50	μS
I <sub>lkg</sub>	Off-state leakage current	Output Hi-Z	--	--	1	μA
r <sub>DS(on)</sub>	FET on-resistance	V <sub>DD</sub> =5V, I <sub>O</sub> =10mA, T <sub>A</sub> =25°C	--	20	--	Ω
t <sub>d</sub>	Output delay time	B=0Gs to B <sub>OP</sub> + 100Gs	--	13	25	μS
t <sub>r</sub>	Output rise time	R1=1Kohm Co=50pF	--	--	0.5	μS
t <sub>f</sub>	Output fall time	R1=1Kohm Co=50pF	--	--	0.2	μS
<b>Magnetic Characteristics</b>						
f <sub>BW</sub>	Bandwidth		20	--	--	kHz
B <sub>OP</sub>	Operated point	TO-92S Package	25	+40	65	Gs
B <sub>RP</sub>	Release point		10	+25	40	Gs
B <sub>HYS</sub>	Hysteresis		7	15	23	Gs
B <sub>OP</sub>	Operated point	SOT23 Package	25	+40	65	Gs
B <sub>RP</sub>	Release point		10	+25	40	Gs
B <sub>HYS</sub>	Hysteresis		7	15	23	Gs
B <sub>OP</sub>	Operated point	SOT23-3 Package	-65	-40	-25	Gs
B <sub>RP</sub>	Release point		-40	-25	-10	Gs
B <sub>HYS</sub>	Hysteresis		-23	-15	-7	Gs

## Function Description Overview

The DH2102 device is a chopper-stabilized Hall sensor with a digital latched output for magnetic sensing applications. The output of the device switches low (turns on) when a magnetic field perpendicular to the Hall element exceeds the operate point threshold,  $B_{OP}$ . After turn-on, the output voltage is  $V_{OUT(sat)}$ . The output transistor is capable of sinking current up to 20mA. When the magnetic field is reduced below the release point,  $B_{RP}$ , the device output goes high (turns off). The difference in the magnetic operate and release points is the hysteresis,  $B_{HYS}$ , of the device. This built-in hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise.

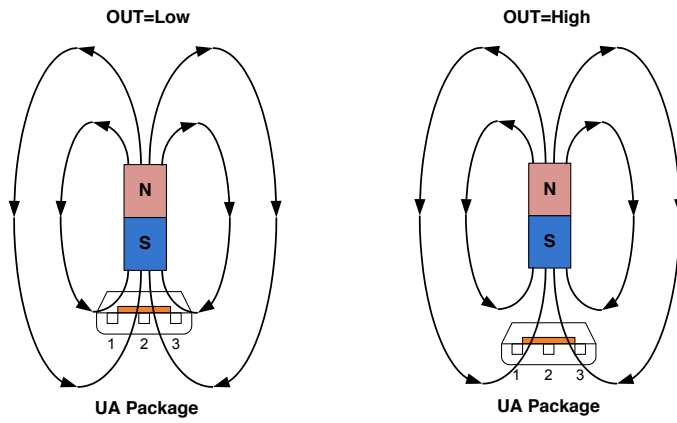
## Functional Block Diagram



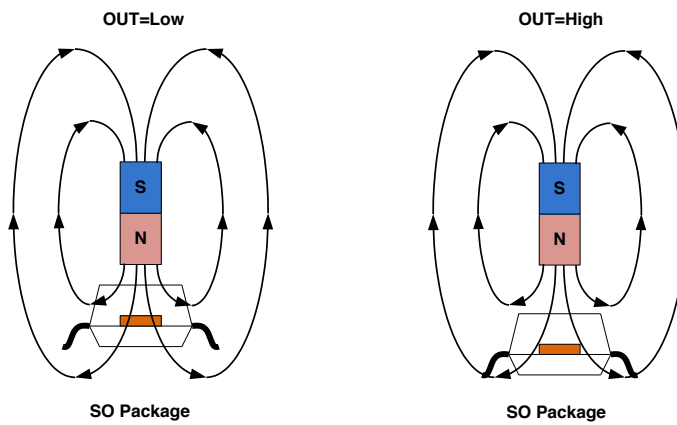
## Field Direction Definition

A positive magnetic field is defined as a south pole near the marked side of the package.

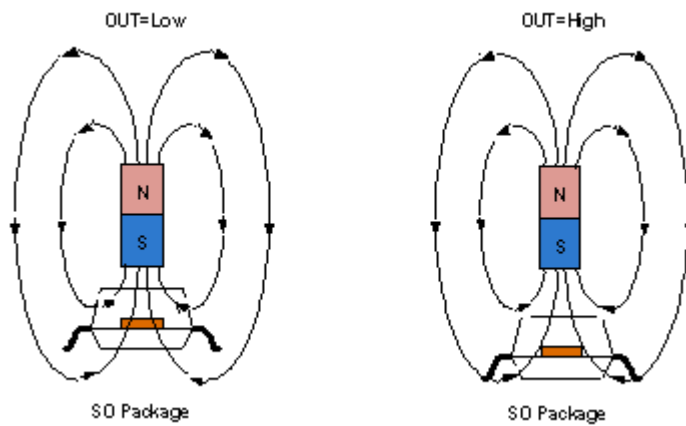
### TO-92S Package



### SOT23-3 Package



### SOT23 Package

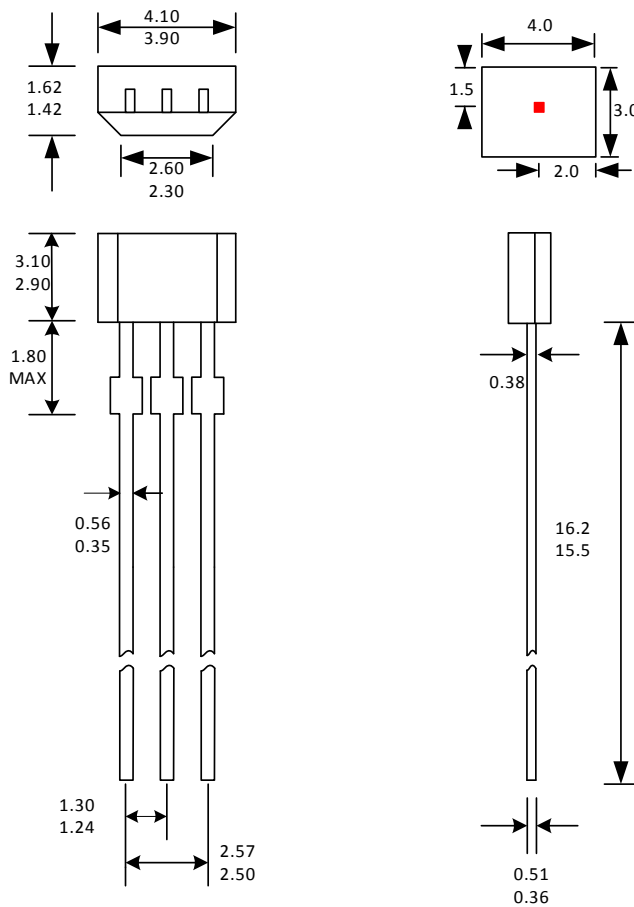


If the device is powered on with a magnetic field strength between  $B_{RP}$  and  $B_{OP}$ , then the device output is determinate High. For UA package, if the field strength is greater than  $B_{OP}$ , then the output is pulled low. If the field strength is less than  $B_{RP}$ , the output is released. For SO package, however, if the field strength is less than  $B_{OP}$ , then the output is pulled low. If the field strength is greater than  $B_{RP}$ , the output is released.

### Package Designator (TO-92S)

3-Terminal  
UA Package

Dimension:mm



#### Notes:

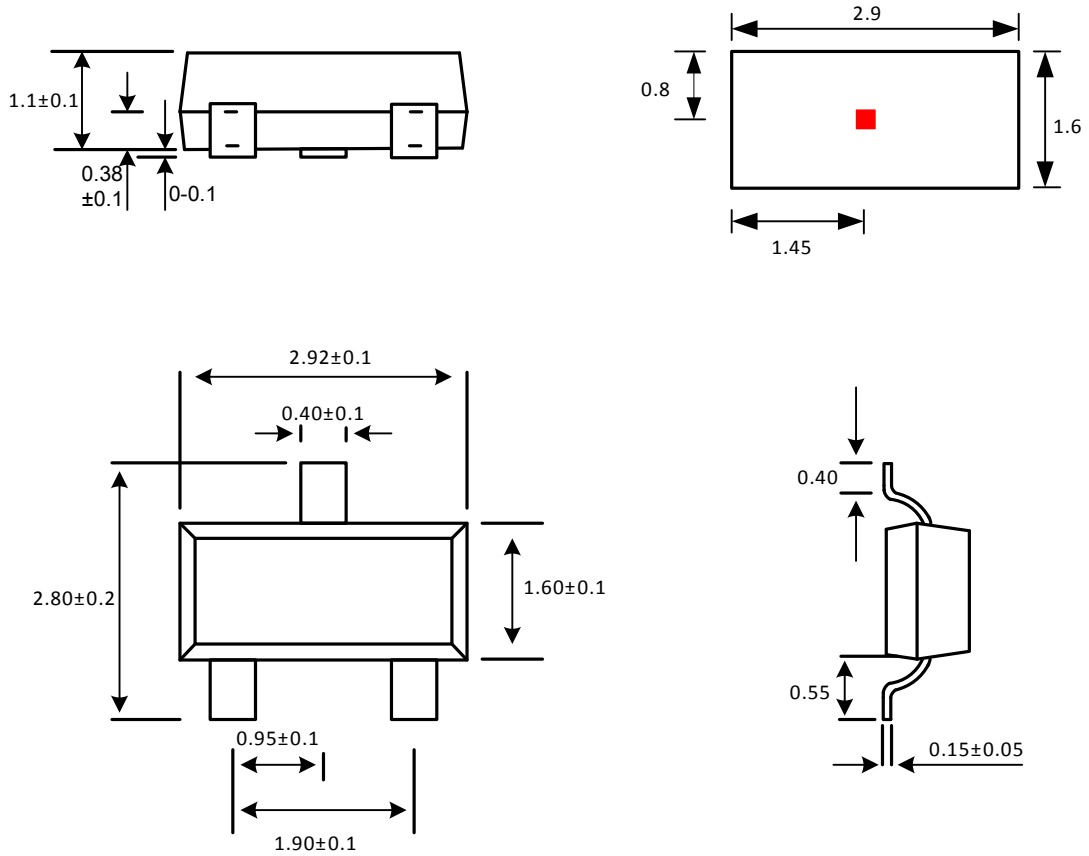
1. Exact body and lead configuration at vendor's option within limits shown.
2. Height does not include mold gate flash.

Where no tolerance is specified, dimension is nominal.

**Package Designator (SOT23-3)**

3-Terminal  
SO Package

Dimension:mm



Notes:

1. Exact body and lead configuration at vendor's option within limits shown.
2. Height does not include mold gate flash.

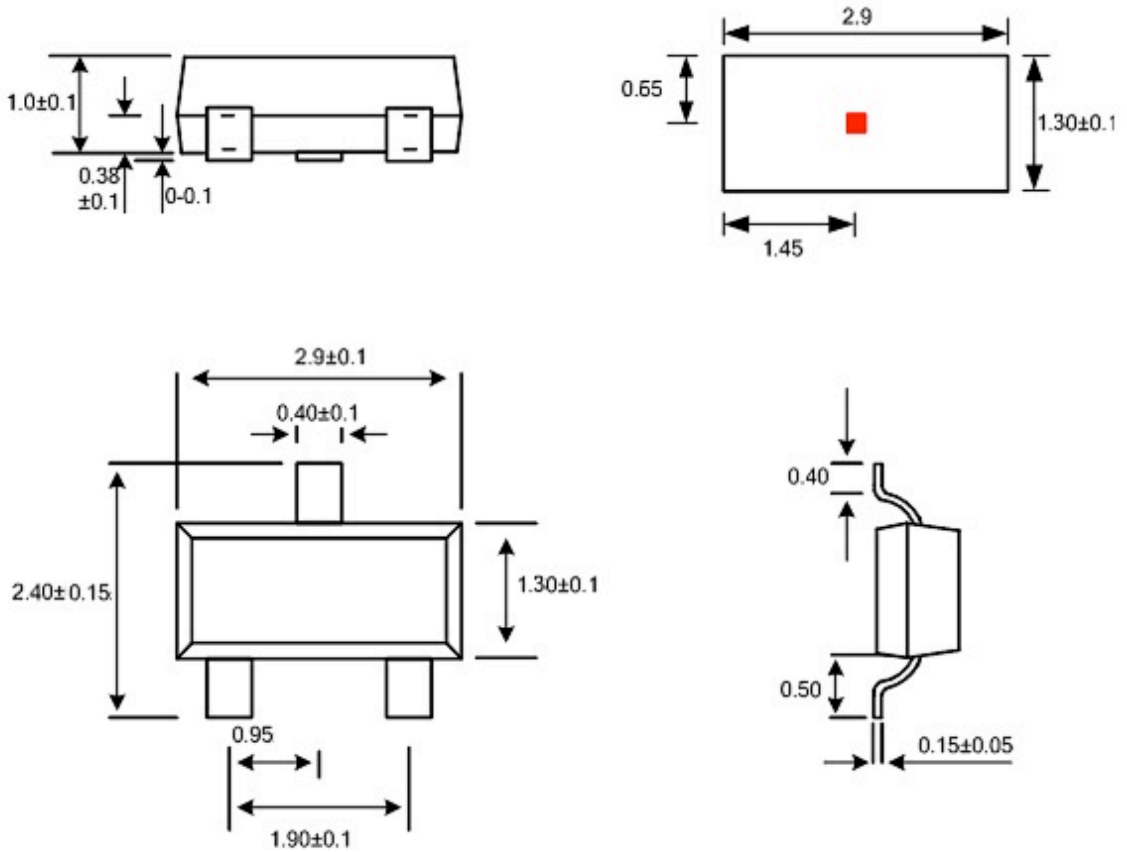
Where no tolerance is specified, dimension is nominal.



### Package Designator (SOT23)

### 3-Terminal SO Package

Dimension:mm



#### Notes:

1. Exact body and lead configuration at vendor's option within limits shown.
2. Height does not include mold gate flash.

Where no tolerance is specified, dimension is nominal.